Sinc-Integral method to solve the linear Schrodinger equation

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Abstract: The integral equation method is presented to solve the linear Schrödinger equation and obtain the eigenvalues. The eigenvalues obtained through this method are compared with Sinc-Collocation method. We show that our method is more accurate than Sinc-Collocation method. Some properties of the Sinc methods required for our subsequent development are given and utilized. Numerical examples are included to demonstrate the validity and applicability of the presented techniques.

Keywords: Linear Schrödinger equation; Sinc-Collocation method; Eigenvalue problem; Volterra integral equations; Fredholm integral equations.

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1 Introduction

In the last three decades, Sinc numerical methods have been extensively used to solve differential equations because of their exponential convergence rate [8, 9, 15, 16]. The aim of this paper is to extend the Sinc techniques to calculate the eigenvalues of Schrödinger equation on interval (a, b), within homogeneous boundary conditions y(a)=y(b)=0 as

\[ cy''(x) + v(x)y(x) = Ey(x), \quad \int_a^b y^2(x)dx = 1 \]  

(1.1)

where unknown value \(E\) and function \(y(x)\) are eigenvalues and eigenfunctions, respectively. Also \(v(x)\) is a known function. We call \(v(x)\) as potential profile. There are various methods to obtain the exact solution of the equation (1.1) [5, 6, 11]. For some potentials, the Eq (1.1) has no exact solution and it must be solved with the numerical methods such as finite difference [2, 3], variational method [3], sinc collocation and sinc galerkin [4], fixed point method [7], homotopy analysis method [4], NU method [12], etc [2, 7, 12]. In this paper we will use the sinc-integral method (SINT) i.e. we convert the equation (1.1) to an equation which contains Volterra and Fredholm integral equations and solve it with sinc collocation method. Some properties of the sinc methods required for our subsequent development are given in the next section. Formalism and Numerical examples are given in section 3 and 4 respectively.

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2 Preliminaries

In the next, a brief overview of Sinc functions is presented. Sinc function properties are thoroughly discussed in [16]. The family of all functions \( f \) that are analytic in a domain \( D \) will be denoted by \( \text{Hol}(D) \). The Sinc function is defined on the whole real line as

\[
\text{Sinc}(x) = \begin{cases} \frac{\sin(x)}{x} & x \neq 0 \\ 1 & x = 0 \end{cases}
\]

(2.1)

For \( h > 0 \), the translated Sinc functions with evenly spaced nodes are given as

\[
S(k, h)(x) = \text{Sinc}\left(\frac{x - kh}{h}\right) \quad k = 0, \pm 1, \pm 2, \ldots
\]

(2.2)

The basis functions on \((a, b)\) are then taken to be the composite translated Sinc functions as

\[
S_k(x) = S(k, h)\phi(x) = \text{Sinc}\left(\frac{\phi(x) - kh}{h}\right) \quad k = 0, \pm 1, \pm 2, \ldots
\]

(2.3)

where \( \phi : (a, b) \rightarrow (-\infty, \infty) \) is a conformal map. Suppose the infinite strip \( D_d \) as

\[
D_d = \{ z \in \mathbb{C} : |\text{Im}(z)| < d \}.
\]

Then the range of \( \phi^{-1} \) is as

\[
\Gamma = \{ \phi^{-1}(t) \in D_d : t \in (-\infty, \infty) \}.
\]

\textbf{Definition 2.1.} Let \( D \) be a simply connected domain which satisfies \((a, b) \subset D \) and \( \alpha \) and \( c \) be positive constants. Then \( L_\alpha(D) \) denotes the family of all functions \( u \in \text{Hol}(D) \) which satisfies

\[
|u(z)| \leq c|Q(z)|^\alpha
\]

for all \( z \in D \) where \( Q(z) = (z - a)(b - z) \).

The following results will be useful to obtain the discretize our system [13].

\textbf{Corollary 2.2.} For \( F \in L_\alpha(D_d) \), positive integer \( N \), \( h = \sqrt{\frac{d}{N}} \) and \( x_i = \phi^{-1}(ih) \), we have:

\[
\int_1 F(x)dx \approx h \sum_{k=-N}^{N} F(x_k) \frac{\phi(x_k)}{\phi'(x_k)}
\]

and

\[
F(x) \approx \sum_{k=-N}^{N} F(x_k)S_k(x)
\]

and

\[
\int_a^z F(t)dt \approx h \sum_{k=-N}^{N} \delta_j^{-1}(\phi(z)) F(z_k) \frac{\phi(z_k)}{\phi'(z_k)}
\]

where

\[
\delta_j^{-1}(z) = \frac{1}{2} + \int_0^t \frac{\sin(\pi t)}{\pi t} dt.
\]
3 Formalism

The integral equation transformed from equation (3.1) is as follows

\[ y(x) = Q(x) \int_a^b k_1(t, y(t)) dt + f(x, y(x)) \int_a^x k(x, t, y(t)) dt. \tag{3.1} \]

This equation is a combination of Volterra and Fredholm integral equations. In these equations, the kernels \( k(x, t, y) \) and \( k_1(t, y) \) are the known function and \( f(x, y) \) is given. To see this, we can rewrite equation (3.1) as follows,

\[ \frac{(E - v(x))y(x)}{c} = y''(x). \]

Then

\[ \int_a^x \frac{(E - v(t))y(t)}{c} dt + c_1 = y'(x). \]

By putting \( x = a \) we have \( c_1 = y'(a) \) and so

\[ \int_a^x \int_a^t \frac{(E - v(t))y(t)}{c} dt dz + xy'(a) + c_2 = y(x). \tag{3.2} \]

Now by putting \( x = a \) and boundary condition \( y(a) = 0 \), we have \( c_2 = -ay'(a) \) and then

\[ y(x) = \int_a^x \int_a^t \frac{(E - v(t))y(t)}{c} dt dz + (x - a)y'(a) \]

\[ = \int_a^x \int_t^x \frac{(E - v(t))y(t)}{c} dz dt + (x - a)y'(a) \]

\[ = \int_a^x (x - t)(E - v(t))y(t) \frac{dt}{c} dz + (x - a)y'(a). \]

Since \( y(b) = 0 \), we have

\[ y'(a) = -\frac{1}{b - a} \int_a^b \frac{(b - t)(E - v(t))y(t)}{c} dt \]

and so

\[ y(x) = -\frac{x - a}{b - a} \int_a^b \frac{(b - t)(E - v(t))y(t)}{c} dt + \int_a^x (x - t)(E - v(t))y(t) \frac{dt}{c}. \tag{3.3} \]

By letting

\[ Q(x) = -\frac{x - a}{b - a}, \]

\[ k_1(t, y(t)) = \frac{(b - t)(E - v(t))y(t)}{c}, \]

\[ f(x, y(x)) = 1 \]
and

\[ k(x, t, y(t)) = \frac{(x - t)(E - v(t))y(t)}{c}, \]

we obtain relation (3.1). Equation (3.1) can be written as:

\[ y(x) = E \left( Q(x) \int_a^b \frac{(b - t)y(t)}{c} dt + \int_a^b \frac{(x - t)y(t)}{c} dt \right) - Q(x) \int_a^b \frac{(b - t)v(t)y(t)}{c} dt - \int_a^b \frac{(x - t)v(t)y(t)}{c} dt. \]  

(3.4)

Now let \( N \) be a positive integer, \( h = \sqrt{\frac{\pi d}{4N}} \) and \( x_j = \phi^{-1}(jh) \) for \( j = -N, ..., N \). By the sinc collocation method, Eq. (3.4) can be written as:

\[ y_j = Ea[i, j] - b[i, j] \]  

(3.5)

where

\[ a[i, j] = \left( Q(x_j)h \sum_{i=-n}^{n} \frac{b - x_i}{c\phi_i} + h \sum_{i=-n}^{n} \frac{x - x_i}{c\phi_i} \delta_{i, j}^{-1} \right) \]

and

\[ b[i, j] = \left( Q(x_j)h \sum_{i=-n}^{n} \frac{(b - x_i)v(x_i)}{c\phi_i'} + h \sum_{i=-n}^{n} \frac{(x - x_i)v(x_i)}{c\phi_i'} \delta_{i, j}^{-1} \right). \]

Then, we can write system (3.5) as

\[ Y = (EA - B)Y \]  

(3.6)

where

\[ A = \begin{bmatrix} a_{1,1} & \cdots & a_{1,2N+1} \\ \vdots & \ddots & \vdots \\ a_{2N+1,1} & \cdots & a_{2N+1,2N+1} \end{bmatrix} \]

\[ B = \begin{bmatrix} b_{1,1} & \cdots & b_{1,2N+1} \\ \vdots & \ddots & \vdots \\ b_{2N+1,1} & \cdots & b_{2N+1,2N+1} \end{bmatrix} \]

\[ Y = \begin{bmatrix} y_1 \\ \vdots \\ y_{2N+1} \end{bmatrix}. \]

Then \( (A^{-1} + A^{-1}B)Y = EY \). So, we can obtain the eigenvalues of matrix \( A^{-1} + A^{-1}B \).

4 Numerical Results

In this section, we consider Eq. (1.1) through various potentials. We apply the Sinc-Integral method to all presented examples in order to obtain eigenvalues and corresponding eigenfunctions. All computations were carried out using Maple software on a personal computer.

Example 4.1. We obtain the energy levels of equation \( F''(x) = EF(x) \) on the interval \((-1, 1)\) with boundary conditions \( F(-1) = F(1) = 0 \). The exact eigenvalues are \( E_{2n+1} = (n + 1)^2 \pi^2 \) and \( E_{2n} = \frac{(2n + 1)^2 \pi^2}{4} \).
For numerical purpose, set $N = 20$ and $h = \sqrt{\frac{1}{N}}$. Table 1 represents the eigenvalues obtained from sinc integral method (SINT), sinc collocation method (SC) and the exact eigenvalues. We denote the absolute errors of SINT and SC methods in eigenvalues with $Er_1 = |E_{\text{exact}} - E_{\text{SINT}}|$ and $Er_2 = |E_{\text{exact}} - E_{\text{SC}}|$, respectively. The error diagrams of ground state energy ($E_0$) and first excite state energy ($E_1$) are shown in figures (1) and (2), respectively.

Table 1: Comparison of energy levels obtained through SINT and SC

<table>
<thead>
<tr>
<th>Eigenvalues</th>
<th>SINT</th>
<th>SC</th>
<th>Exact</th>
<th>$Er_1$</th>
<th>$Er_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$E_0$</td>
<td>2.467403807</td>
<td>2.469915656</td>
<td>2.467401101</td>
<td>$2.706 \times 10^{-6}$</td>
<td>$2.514555 \times 10^{-3}$</td>
</tr>
<tr>
<td>$E_1$</td>
<td>9.869648165</td>
<td>9.879665536</td>
<td>9.869604404</td>
<td>$4.3761 \times 10^{-8}$</td>
<td>$1.0061132 \times 10^{-4}$</td>
</tr>
<tr>
<td>$E_2$</td>
<td>22.20683118</td>
<td>22.22992838</td>
<td>22.20660991</td>
<td>$2.2127 \times 10^{-4}$</td>
<td>$2.263847 \times 10^{-2}$</td>
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<tr>
<td>$E_3$</td>
<td>39.47911556</td>
<td>39.51865187</td>
<td>39.47841762</td>
<td>$6.974 \times 10^{-4}$</td>
<td>$4.023425 \times 10^{-2}$</td>
</tr>
</tbody>
</table>

Figure 1: Error diagram of ground state energy ($E_0$) as a function of number of nodes

**Example 4.2.** We obtain the energy levels of equation $F''(x) + x = EF(x)$ on the interval $(-1, 1)$ with boundary conditions $F(-1) = F(1) = 0$. For numerical purpose, set $N = 20$ and $h = \sqrt{\frac{1}{N}}$. Table 1 represents the eigenvalues obtained from sinc integral method (SINT) and sinc collocation method (SC). The diagrams of ground state energy ($E_0$) and first excite state energy are ($E_1$) shown in figures (1) and (2), respectively.

Table 2: Comparison of energy levels obtained through SINT and SC

<table>
<thead>
<tr>
<th>Eigenvalues</th>
<th>SINT</th>
<th>SC</th>
</tr>
</thead>
<tbody>
<tr>
<td>$E_0$</td>
<td>2.449871300</td>
<td>2.452422493</td>
</tr>
<tr>
<td>$E_1$</td>
<td>9.874861653</td>
<td>9.884863364</td>
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<td>$E_2$</td>
<td>22.20995024</td>
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<tr>
<td>$E_3$</td>
<td>39.48102540</td>
<td>39.52055000</td>
</tr>
</tbody>
</table>
5 Conclusion

In this paper, the Sinc integral method is applied to the Schrödinger equation with homogeneous boundary conditions. The energy level obtained through Sinc integral and Sinc collocation methods are compared with each other and also with exact the solution. From the errors in the table (1), and figures (1), (2), the values of our method is more closer to the exact values. Also, from figures (3) and (4), Sinc integral method for the smaller values of $n$ is more closer to the previous results.
Sinc-Integral method to solve the linear Schrodinger equation

Figure 4: Diagram of ground state energy ($E_1$) as a function of number of nodes

References


