

Algorithms for determining the type of algebraic hyperstructures and morphisms

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Abstract: In this paper, we present some primary methods to define a hypergroupoid by algorithm. Then, we present algorithms for checking if it is closed under \circ , associativity, weak associativity, commutativity, weak commutativity, establishing the reproduction axiom, determining the type of a hypergroupoid (H, \circ) and the type of a morphism f in a hypergroupoid (H, \circ) . The goal of this paper is to provide algorithms for checking the basic features and morphisms in algebraic hyperstructures. Our attention is on algorithms for algebraic hyperstructures with one hyperoperation (i.e. hypergroupoids). The algorithms can be developed for other algebraic hyperstructures.

Keywords: Algorithm; Hypergroupoid; Hypergroup; H_v -group; Algebraic Hyperstructure; Homomorphism

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1 Introduction

The concept of algebraic hyperstructures was introduced in 1934 by Marty [9], at the 8th Congress of Scandinavian Mathematicians and has been studied in the following decades and nowadays by many mathematicians. In a classical algebraic structure, the composition of two elements is an element, while in an algebraic hyperstructure, the composition of two elements results in a set of elements [5, p. 1]. The development of algebraic hyperstructures has made significant theoretical progress in recent years. These developments are more focused on pure topics and less attention has been given to presenting algorithm.

For example, although checking the basic features in classical algebraic structures can be done by software, e.g. by "GAP[8]", but checking them in algebraic hyperstructures has not been provided by any software. The reason for this is the lack of the necessary algorithms in this field. So far, few algorithms have been presented in algebraic hyperstructures. For example, we can refer to [1, 13, 11, 10, 2, 15, 16, 14, 12, 6]. Most of these algorithms only enumerate some specific algebraic hyperstructures (such as Rosenberg hypergroups). But none of them have provided algorithms to check the basic features and morphisms in algebraic hyperstructures.

This paper is an attempt to solve this deficiency by presenting basic algorithms. Algorithms will be presented in such a way that they can be easily implemented in mathematical software and programming languages. Also, the Maple codes for the algorithms are provided at the end of each part.

There are several important questions about these issues that we try to answer them in this paper:

- How to define a hypergroupoid (H, \circ) by algorithm?

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- How can we check the basic features, such as associativity and commutativity, in a hypergroupoid (H, \circ) by algorithm?
- How to determine the type of a homomorphism f ?

We investigate about the following issues for hypergroupoids:

- Defining a hypergroupoid (H, \circ) , which led to Algorithms 1 and 2 and additional Algorithm 3;
- Checking the basic features and determining the type of a hypergroupoid (H, \circ) by algorithm, which led to Algorithms 4, 5, 6, 7, 8, 9, 10 and 11;
- Determining the type of a homomorphism f , which led to Algorithm 12.

In issue a), using the mentioned algorithms, we can easily define a hypergroupoid (H, \circ) . In example 3.2 and the paragraph after that, these algorithms are stated and how they are used to define a hypergroupoid (H, \circ) is presented. It should be noted that the mentioned methods for defining hypergroupoid (H, \circ) are primary, and dear reader can use more complex methods, e.g. using generators, in defining hypergroupoid (H, \circ) . The only thing that should be observed is the number and type of inputs and outputs, which we have discussed in its place.

In issue b), using the mentioned algorithms, we can confirm the basic features by algorithms. These features are closedness, associativity, weak associativity, commutativity, weak commutativity and reproduction axiom. (A weak relation means that instead of equality, it is a non-empty intersection and reproduction axiom means $xH = H$ for any $x \in H$). Other features can be check similarly by algorithms. Also, Algorithm 11 is presented to determine the type of a hypergroupoid (H, \circ) based on these features, such as semihypergroup, H_v -group and so on.

In issue c), using the mentioned algorithm, we can determine the type of a mapping f . This algorithm can be extended for other algebraic hyperstructures. This algorithm can be easily developed to check other features and return the appropriate output.

2 Preliminaries

In this section, we recall some required definitions in algebraic hyperstructures. The content of this section is mostly adopted from [5, 7, 3].

Let H be a non-empty set. A mapping $\circ : H \times H \rightarrow \mathcal{P}^*(H)$, where $\mathcal{P}^*(H)$ denotes the family of all non-empty subsets of H , is called a *hyperoperation* on H . The couple (H, \circ) is called a *hypergroupoid*. A hypergroupoid (H, \circ) is called *finite* if H has only a finitely many elements.

Let A and B are two non-empty subsets of H and $a, b \in H$, then we denote

$$A \circ B = \bigcup_{\substack{x \in A \\ y \in B}} x \circ y, \quad a \circ B = \{a\} \circ B = \bigcup_{y \in B} a \circ y, \quad A \circ b = A \circ \{b\} = \bigcup_{x \in A} x \circ b.$$

Other required definitions will come in place.

Example 2.1. [4] Let $H = \{O, A, B, AB\}$. Define the hyperoperation \circ on H by the following table:

\circ	O	A	B	AB
O	$\{O\}$	$\{O, A\}$	$\{O, B\}$	$\{A, B\}$
A	$\{O, A\}$	$\{O, A\}$	$\{AB, A, B, O\}$	$\{AB, A, B\}$
B	$\{O, B\}$	$\{AB, A, B, O\}$	$\{O, B\}$	$\{AB, A, B\}$
O	$\{A, B\}$	$\{AB, A, B\}$	$\{AB, A, B\}$	$\{AB, A, B\}$

This is ABO blood table. The (H, \circ) is a hypergroupoid. This hypergroupoid is used for future algorithms as an example.

3 Algorithms

In this section, we first present methods for defining hypergroupoid (H, \circ) (subsection 3.1). Then, in subsection 3.2, we examine the basic features of hypergroupoids. Finally, in subsection 3.3, we present algorithms for checking morphisms.

In writing algorithms, modularity has been observed, so that minimal changes are required when changing or updating algorithms.

3.1 Defining algebraic hyperstructures by algorithm

In this subsection, we present two methods for defining a finite hypergroupoid (H, \circ) . First, we need to define the set H and hyperoperation \circ on H appropriately for using in next algorithms. If the set H is infinite, the algorithms are logically correct but may not terminate. Therefore, we suppose that the set H is finite.

The set H can be easily implemented by tools available in programming languages or mathematical software. In these languages and software, there is often a tool called “set” to define the set. We can also use “linked list” or “dynamic array” to define the set. We can implement hyperoperation \circ as a “procedure” or “function” that takes two inputs, such as $a, b \in H$, and returns the desired output, i.e. $a \circ b \subseteq H$. This method of implementation of hyperoperation \circ in programming languages or mathematical software frees us from the details of defining hyperoperation. We may define hyperoperation using a table of hyperoperation, or we may define hyperoperation using generator members, or in any desired method. The details of implementation of hyperoperation \circ are not important, the only thing that matters in implementation of hyperoperation \circ is that it is defined as a procedure or function that takes two inputs, say $a, b \in H$, and returns the corresponding set, say $a \circ b \subseteq H$. In example 3.2, we have shown an algorithm for defining hyperoperation \circ using the table of hyperoperation. Although the table of hyperoperation is the simplest method to define hyperoperation, it is not an optimal method in programming. Example 3.2 is just a simple example for implementation of hyperoperation using a table of hyperoperation.

Also, we need an array to specify the order of members of set H . See Example 3.1.

Example 3.1. Let $H = \{b, c, a, d\}$. So, we have $|H| = 4$. Suppose the order of members of set H is equal to array $\mathbf{A}_H = [a \ b \ c \ d]$. We call the array \mathbf{A}_H , the array of order of elements of H . In example 2.1, we have $\mathbf{A}_H = [O \ A \ B \ AB]$. This array is equal to the first row or first column of the table of hyperoperation \circ .

We denote the index of an element $a \in H$ by a_{index} in terms of array \mathbf{A}_H (with default name “ a_{index} ” in Maple codes). We need a procedure, named “*WhatIndex*”, for this. In Maple, the procedure “*Search*” finds the index of an entry in an array. We can define procedure *WhatIndex* based on this procedure, or define by a loop “for”. For using it, we simply write $a_{\text{index}} := \text{WhatIndex}(a, \mathbf{A}_H)$.

Now, we define a hypergroupoid by algorithm in Example 3.2.

Example 3.2. Consider Example 2.1. We have $H = \{O, A, B, AB\}$ and the hyperoperation \circ on H by the following table:

\circ	O	A	B	AB
O	$\{O\}$	$\{O, A\}$	$\{O, B\}$	$\{A, B\}$
A	$\{O, A\}$	$\{O, A\}$	$\{AB, A, B, O\}$	$\{AB, A, B\}$
B	$\{O, B\}$	$\{AB, A, B, O\}$	$\{O, B\}$	$\{AB, A, B\}$
O	$\{A, B\}$	$\{AB, A, B\}$	$\{AB, A, B\}$	$\{AB, A, B\}$

First we define and calculate three variables. For any hypergroupoid, we need these variables to define the procedure of hyperoperation \circ . It doesn't matter by which method hyperoperation \circ is defined.

$H = \{O, A, B, AB\};$
 $|H| = \text{cardinal of } H;$
 $\mathbf{A}_H = [O \ A \ B \ AB].$

By array \mathbf{A}_H , we calculate the index of each member in the set H according to the position of it in the array. For example, the index of B in the \mathbf{A}_H is equal to 3 and we write $B_{\text{index}} = 3$. This index can be found by procedure *WhatIndex* (discussed before). Therefore, we can write $B_{\text{index}} := \text{WhatIndex}(B, \mathbf{A}_H)$.

Now, according to the above table, we can define hyperoperation \circ .

First, we define a matrix with dimension $|H| \times |H|$, called \mathbf{Table}_\circ . The value of each entry in the matrix \mathbf{Table}_\circ is determined according to the table of hyperoperation \circ and array \mathbf{A}_H .

Therefore, we have:

$$\mathbf{Table}_\circ := \begin{bmatrix} \{O\} & \{A, O\} & \{B, O\} & \{A, B\} \\ \{A, O\} & \{A, O\} & \{A, AB, B, O\} & \{A, AB, B\} \\ \{B, O\} & \{A, AB, B, O\} & \{B, O\} & \{A, AB, B\} \\ \{A, B\} & \{A, AB, B\} & \{A, AB, B\} & \{A, AB, B\} \end{bmatrix}$$

Based on \mathbf{Table}_\circ , hyperoperation \circ is presented in Algorithm 1 and procedure \circ corresponds to hyperoperation \circ .

Algorithm 1: Defining hyperoperation \circ based on matrix \mathbf{Table}_\circ .

```

1 Input: Matrix  $\mathbf{Table}_\circ$ ,  $a \in H$ ,  $b \in H$ 
2 Output: Set  $a \circ b$ 
3 Procedure: hyperoTable( $\mathbf{Table}_\circ$  : matrix,  $a, b$ ) : set
4 return  $\mathbf{Table}_\circ[\text{WhatIndex}(a, \mathbf{A}_H), \text{WhatIndex}(b, \mathbf{A}_H)]$ 
5
1 Input:  $a \in H$ ,  $b \in H$ 
2 Output: Set  $a \circ b$ 
3 Procedure:  $\circ(a, b)$ 
4 return hyperoTable( $\mathbf{Table}_\circ$ ,  $a, b$ )

```

Algorithm 1 returns the value of the set $a \circ b$ using the indices corresponding to a and b and the matrix \mathbf{Table}_\circ .

If the hyperoperation \circ in hypergroupoid (H, \circ) is defined by mapping $f : H \times H \rightarrow \mathcal{P}^*(H)$, instead of the table of hyperoperation \circ , we can easily define procedures \circ as follows:

Algorithm 2: Defining hyperoperation for hypergroupoid (H, \circ) by mapping $f : H \times H \rightarrow \mathcal{P}^*(H)$

```

1 Input:  $a \in H$ ,  $b \in H$ 
2 Output: Set  $a \circ b$ 
3 Procedure:  $\circ(a, b)$  : set
4 return  $f(a, b)$ 

```

For Example 3.2, the Maple codes for set H , array \mathbf{A}_H , $|H|$ and \mathbf{Table}_\circ is as follow. In Maple, Boolean variables are initialized with "true" and "false" values, instead of 0 and 1. In these codes, we denote the $|H|$ by variable *cardH*.

```

H:={O,A,AB,B};
cardH:=numelems(H);
AH:=Array([O,A,B,AB]);
#-----
Table0:=Matrix(cardH,cardH):
Table0[1,1]:={O}:
Table0[1,2]:={O,A}:

```

```

Table0[1,3]:={0,B}:
Table0[1,4]:={A,B}:
Table0[2,1]:={0,A}:
Table0[2,2]:={0,A}:
Table0[2,3]:={0,A,B,AB}:
Table0[2,4]:={A,B,AB}:
Table0[3,1]:={0,B}:
Table0[3,2]:={0,A,B,AB}:
Table0[3,3]:={0,B}:
Table0[3,4]:={A,B,AB}:
Table0[4,1]:={A,B}:
Table0[4,2]:={A,B,AB}:
Table0[4,3]:={A,B,AB}:
Table0[4,4]:={A,B,AB}:
Table0;

```

The following procedures are written in Maple based on Algorithm 1. In Maple, to find the index of a member in an array, there is a ready-made procedure called “Search”, which is located in package “ListTools” and is called by command “with(ListTools)”. This procedure uses a loop “for” to search the index of a member in an array and when it reaches the desired member, it returns the value of the loop variable as the index. We present the procedure $\text{WhatIndex}(a, A_H)$ in Maple based on procedure “Search” as follow.

Now, using the above codes, we can define the procedures of hyperoperation “*hypero*” as follows in Maple.

```

with(ListTools):
#-----
WhatIndex:=proc(a,AH::Array,$)::integer;
return Search(a,AH);
end proc:
#-----
hyperoTable:=proc(Table0::Matrix,a,b,$)::set;
return Table0[WhatIndex(a,AH),WhatIndex(b,AH)];
end proc:
#-----
hypero:=proc(a,b,$)::set;
return hyperoTable(Table0,a,b);
end proc:
#-----

```

For mapping $f : H \times H \rightarrow \mathcal{P}^*(H)$, the procedures of hyperoperation \circ , based on Algorithm 2, can be defined directly in Maple as follow.

```

hypero:=proc(a,b,$)::set;
return f(a,b);
end proc:
#-----

```

Now, we present algorithms for calculating expressions $a \circ b$, $a \circ B$, $A \circ b$ and $A \circ B$. In the algorithms in next subsections, we will use the procedures defined based on the Algorithm 3, instead of directly calling the procedure of hyperoperation “ \circ ”, in the body of the algorithms. In Algorithm 3, with proper inputs, the sets $a \circ b$, $a \circ B$, $A \circ b$ and $A \circ B$, based on their definitions in section 2, are calculated and returned.

Algorithm 3: Calculating sets $a \circ b$, $a \circ B$, $A \circ b$, $A \circ B$

```

1 Input: Hyperoperation  $\circ$ ,  $a \in H$ ,  $b \in H$ 
2 Output: Set  $a \circ b$ 
3 Procedure:  $aob(\circ : \text{procedure}, a, b) : \text{set}$ 
4 return  $a \circ b$  /*  $a \circ b = \circ(a, b)$  */
5


---


1 Input: Hyperoperation  $\circ$ ,  $a \in H$ , Set  $B \subseteq H$ 
2 Output: Set  $a \circ B$ 
3 Procedure:  $aoB(\circ : \text{procedure}, a, B : \text{set}) : \text{set}$ 
4  $aB := \emptyset$ 
5 for  $b \in B$  do
6    $aB := aB \cup a \circ b$  /*  $a \circ b = aob(\circ, a, b)$  */
7 end for
8 return  $aB$ 
9


---


1 Input: Hyperoperation  $\circ$ , Set  $A \subseteq H$ ,  $b \in H$ 
2 Output: Set  $A \circ b$ 
3 Procedure:  $Aob(\circ : \text{procedure}, A : \text{set}, b) : \text{set}$ 
4  $Ab := \emptyset$ 
5 for  $a \in A$  do
6    $Ab := Ab \cup a \circ b$  /*  $a \circ b = aob(\circ, a, b)$  */
7 end for
8 return  $Ab$ 
9


---


1 Input: Hyperoperation  $\circ$ , Set  $A \subseteq H$ , Set  $B \subseteq H$ 
2 Output: Set  $A \circ B$ 
3 Procedure:  $AoB(\circ : \text{procedure}, A : \text{set}, B : \text{set}) : \text{set}$ 
4  $AB := \emptyset$ 
5 for  $a \in A$  do
6    $AB := AB \cup a \circ B$  /*  $a \circ B = aoB(\circ, a, B)$  */
7 end for
8 return  $AB$ 

```

Procedure call: $aob(\circ, a, b)$, $aoB(\circ, a, B)$, $Aob(\circ, A, b)$, $AoB(\circ, A, B)$

The Maple codes of Algorithm 3 is as follow:

```

aob:=proc(hypero::procedure, a, b, $)::set;
  return hypero(a,b);
end proc;
#-----
aoB:=proc(hypero::procedure, a, B::set, $)::set;
  local aB::set, b;
  aB:={};
  for b in B do
    aB:=aB union aob(hypero, a, b);
  end do;
  return aB;
end proc;
#-----
Aob:=proc(hypero::procedure, A::set, b, $)::set;

```

```

local Ab::set,a;
Ab:={};
for a in A do
  Ab:=Ab union aob(hypero,a,b);
end do;
return Ab;
end proc;
#-----
AoB:=proc(hypero::procedure,A::set,B::set,$)::set;
local AB::set,a;
AB:={};
for a in A do
  AB:=AB union aoB(hypero,a,B);
end do;
return AB;
end proc;
#-----

```

To call the above procedures in Maple, it can be done like the following commands:
`aoB(hypero,a,{a,b});`

3.2 Algorithms for some basic features

In previous subsection, a hypergroupoid (H, \circ) was defined by algorithm. In this subsection, using the Algorithm 3, we can easily consider the basic features introduced for algebraic hyperstructures. This algorithms can be used as a template to providing algorithms to determine other features in algebraic hyperstructures.

Indeed, by algorithm, we can check the basic features of a hypergroupoid (H, \circ) , such as closedness under \circ , associativity, weak associativity, reproduction axiom, ..., and also we can determine the type of (H, \circ) , such as semihypergroup, hypergroup, etc. . The output of the algorithms in this subsection, except for Algorithm 11, is either **true** or **false**.

First, we need several definitions that are recalled from [5, 7, 3]. Some of them are presented with a slight change.

Let (H, \circ) be a hypergroupoid and $K \subseteq H$. We say K in hypergroupoid (H, \circ) is

- “closed under \circ ” if for all $a, b \in K$ we have $a \circ b \in K$;
- “associative” if for all $a, b, c \in K$ we have $a \circ (b \circ c) = (a \circ b) \circ c$;
- “weak associative” if for all $a, b, c \in K$ we have $a \circ (b \circ c) \cap (a \circ b) \circ c \neq \emptyset$;
- “commutative” if for all $a, b \in K$ we have $a \circ b = b \circ a$;
- “weak commutative” if for all $a, b \in K$ we have $a \circ b \cap b \circ a \neq \emptyset$.

We say that set $K \subseteq H$ in hypergroupoid (H, \circ) satisfy “reproduction axiom” if for all $a \in K$, we have $a \circ K = K \circ a = K$.

A hypergroupoid (H, \circ) is called

- “semihypergroup” if H in hypergroupoid (H, \circ) is associative;
- “quasihypergroup” if H in hypergroupoid (H, \circ) satisfies reproduction axiom;
- “ H_v -semigroup” if H in hypergroupoid (H, \circ) is weak associative;
- “ H_v -group” if H in hypergroupoid (H, \circ) satisfies reproduction axiom and H in hypergroupoid (H, \circ) is weak associative;

- “hypergroup” if H in hypergroupoid (H, \circ) satisfies reproduction axiom and H in hypergroupoid (H, \circ) is associative;

Algorithm 4 checks the closedness of $K \subseteq H$ in hypergroupoid (H, \circ) under \circ , based on above definition.

Algorithm 4: Checking closedness of $K \subseteq H$ in hypergroupoid (H, \circ) under \circ

```

1 Input: Hyperoperation  $\circ$ , Set  $K$ 
2 Output: Is set  $K \subseteq H$  in  $(H, \circ)$  closed under hyperoperation  $\circ$ ?
3 Procedure:  $IsClosed(\circ : procedure, K : set) : boolean$ 
4  $b := true$ 
5 for  $x \in K$  do
6   for  $y \in K$  do
7     if  $x \circ y \not\subseteq K$  then                                     /*  $x \circ y = aob(\circ, x, y)$  */
8        $b := false$ 
9       break
10      break
11     end if
12   end for
13 end for
14 return  $b$ 

```

Procedure call: $IsClosed(\circ, K)$

In Algorithm 4, the closedness of set $K \subseteq H$ in hypergroupoid (H, \circ) under \circ is checked. It should be noted that in order for (H, \circ) to be a hypergroupoid, it is enough that the set H to be closed under \circ . Therefore in Algorithm 4, it is enough to substitute the set H for K .

Now, we present algorithms to check the associativity and weak associativity of a set $K \subseteq H$ in a hypergroupoid (H, \circ) .

By Algorithm 5, we can check the associativity of set $K \subseteq H$ in hypergroupoid (H, \circ) . If set K in (H, \circ) is associative, then it return “true”, otherwise it return “false”.

Algorithm 5: Associativity of a set $K \subseteq H$ in hypergroupoid (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $K \subseteq H$ 
2 Output: Is set  $K \subseteq H$  in  $(H, \circ)$  associative?
3 Procedure:  $IsAssociative(\circ : procedure, K : set) : boolean$ 
4  $b := true$ 
5 for  $x \in K$  do
6   for  $y \in K$  do
7     for  $z \in K$  do
8       if  $x \circ (y \circ z) \neq (x \circ y) \circ z$  then                 /*  $x \circ (y \circ z) = aoB(\circ, x, aob(\circ, y, z))$  */
9          $b := false$                                            /*  $(x \circ y) \circ z = Aob(\circ, aob(\circ, x, y), z)$  */
10        break
11       break
12      break
13     end if
14   end for
15 end for
16 end for
17 return  $b$ 

```

Procedure call: $\text{IsAssociative}(\circ, K)$

By Algorithm 6, we can check the weak associativity of a set $K \subseteq H$ in hypergroupoid (H, \circ) . If set K in (H, \circ) is weak associative, it returns "true", otherwise it returns "false". This algorithm is similar to Algorithm 5 and only different is in the conditional statement.

Algorithm 6: Weak associativity of a set $K \subseteq H$ in hypergroupoid (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $K \subseteq H$ 
2 Output: Is set  $K \subseteq H$  in  $(H, \circ)$  weak associative?
3 Procedure:  $\text{IsWeakAssociative}(\circ : \text{procedure}, K : \text{set}) : \text{boolean}$ 
4  $b := \text{true}$ 
5 for  $x \in K$  do
6   for  $y \in K$  do
7     for  $z \in K$  do
8       if  $x \circ (y \circ z) \cap (x \circ y) \circ z = \emptyset$  then                                /*  $x \circ (y \circ z) = \text{aob}(\circ, x, \text{aob}(\circ, y, z))$  */
9          $b := \text{false}$                                                                 /*  $(x \circ y) \circ z = \text{Aob}(\circ, \text{aob}(\circ, x, y), z)$  */
10        break
11        break
12        break
13      end if
14    end for
15  end for
16 end for
17 return  $b$ 

```

Procedure call: $\text{IsWeakAssociative}(\circ, K)$

The next two algorithms check the commutativity and weak commutativity of a set $K \subseteq H$ in hypergroupoid (H, \circ) and return the result as "true" or "false".

Algorithm 7 checks the commutativity of a set $K \subseteq H$ in hypergroupoid (H, \circ) . If set K in (H, \circ) is commutative, it return "true", otherwise it return "false".

Algorithm 7: Commutativity of a set $K \subseteq H$ in hypergroupoid (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $K$ 
2 Output: Is set  $K \subseteq H$  in  $(H, \circ)$  commutative?
3 Procedure:  $\text{IsCommutative}(\circ : \text{procedure}, K : \text{set}) : \text{boolean}$ 
4  $b := \text{true}$ 
5 for  $x \in K$  do
6   for  $y \in K$  do
7     if  $x \circ y \neq y \circ x$  then
8        $b := \text{false}$                                                                 /*  $x \circ y = \text{aob}(\circ, x, y)$  and ... */
9       break
10      break
11    end if
12  end for
13 end for
14 return  $b$ 

```

Procedure call: $\text{IsCommutative}(\circ, K)$

By Algorithm 8, we can check the weak commutativity of a set $K \subseteq H$ in hypergroupoid (H, \circ) . If set K in (H, \circ) is weak commutative, it returns "true", otherwise it returns "false". This algorithm is similar to Algorithm 7 and only different is in the conditional statement.

Algorithm 8: Weak commutativity of a set $K \subseteq H$ in hypergroupoid (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $K$ 
2 Output: Is set  $K \subseteq H$  in  $(H, \circ)$  weak commutative?
3 Procedure: IsWeakCommutative( $\circ$  : procedure,  $K$  : set) : boolean
4  $b := true$ 
5 for  $x \in K$  do
6   for  $y \in K$  do
7     if  $x \circ y \cap y \circ x = \emptyset$  then
8        $b := false$                                 /*  $x \circ y = aob(\circ, x, y)$  and ... */
9       break
10      break
11     end if
12   end for
13 end for
14 return  $b$ 

```

Procedure call: *IsWeakCommutative*(\circ, K)

Now, we present the algorithm for checking the reproduction axiom in a set $K \subseteq H$ in hypergroupoid (H, \circ) using its definition.

Algorithm 9, using the definition, first checks the equality $a \circ K \neq K$ for each member $a \in K$. If it is not satisfied, it stores the result in variable b and break loop "for". Otherwise it checks the equality $K \circ a \neq K$. If it is not confirmed, it stores the result in variable b and break loop "for". Finally, it returns the variable b as the result of the algorithm.

Algorithm 9: Checking reproduction axiom in a set $K \subseteq H$ in hypergroupoid (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $K$ 
2 Output: Is reproduction axiom satisfied in set  $K \subseteq H$  in  $(H, \circ)$ ?
3 Procedure: IsReproduction( $\circ$  : procedure,  $K$  : set) : boolean
4  $b := true$ 
5 for  $a \in K$  do
6   if  $a \circ K \neq K$  then                                /*  $a \circ K = aob(\circ, a, K)$  */
7      $b := false$ 
8     break
9   else if  $K \circ a \neq K$  then                            /*  $K \circ a = Aob(\circ, K, a)$  */
10     $b := false$ 
11    break
12   end if
13 end for
14 return  $b$ 

```

Procedure call: *IsReproduction*(\circ, K)

By Algorithm 10, we can determine whether (H, \circ) is a hypergroupoid. This algorithm determines whether H is a non-empty set and whether mapping \circ is a hyperoperation on H .

Algorithm 10: Cchecking hypergroupoidness of (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $H$ 
2 Output: Is  $(H, \circ)$  a hypergroupoid?
3 Procedure: IsHypergroupoid( $\circ$  : procedure,  $H$  : set) : boolean
4  $b := true$ 
5 if  $H = \emptyset$  then
6    $b := false$ 
7 else
8   for  $x \in H$  do
9     for  $y \in H$  do
10       $T := x \circ y$  /*  $x \circ y = aob(\circ, x, y)$  */
11      if  $T = \emptyset$  then
12         $b := false$ 
13        break
14        break
15      else if  $T \not\subseteq H$  then
16         $b := false$ 
17        break
18        break
19      end if
20    end for
21  end for
22 end if
23 return  $b$ 

```

Procedure call: *IsHypergroupoid*(\circ, H)

Now, we can determine the type of a hypergroupoid (H, \circ) among the hypergroupoid, semi-hypergroup, quasi-hypergroup, H_v -semigroup, H_v -group and hypergroup. Algorithm 11 does this. It is better to use this algorithm after we have made sure that (H, \circ) is a hypergroupoid (for example, using Algorithms 10), because the precondition of Algorithm 11 is that their input is a hypergroupoid. This algorithm can be extended to include other types of algebraic hyperstructures.

Algorithm 11 determines the type of an algebraic hyperstructure (H, \circ) .

Algorithm 11: Determining the type of an algebraic hyperstructure (H, \circ)

```

1 Input: Hyperoperation  $\circ$ , Set  $H$ 
2 Output: What is the type of  $(H, \circ)$ ?
3 Procedure: WhatIsTypeOf( $\circ$  : procedure,  $H$  : set) : string
4  $associative := IsAssociative(\circ, H)$ 
5 if  $associative = true$  then  $weakassociative := true$ 
6 else  $weakassociative := IsWeakAssociative(\circ, H)$ 
7 end if
8  $commutative := IsCommutative(\circ, H)$ 
9 if  $commutative = true$  then  $weakcommutative := true$ 
10 else  $weakcommutative := IsWeakCommutative(\circ, H)$ 
11 end if
12  $reproduction := IsReproduction(\circ, H)$ 
13 if  $associative = weakassociative = reproduction = true$  then

```

```

14 BaseType := "Hypergroup"
15 else if (weakassociative = reproduction = true)  $\wedge$  (associative = false) then
16   BaseType := "Hv – group"
17 else if (associative = weakassociative = true)  $\wedge$  (reproduction = false) then
18   BaseType := "Semihypergroup"
19 else if (weakassociative = true)  $\wedge$  (associative = reproduction = false) then
20   BaseType := "Hv – semigroup"
21 else if (reproduction = true)  $\wedge$  (associative = weakassociative = false) then
22   BaseType := "Quasihypergroup"
23 else BaseType := "Hypergroupoid"
24 end if
25 if commutative = weakcommutative = true then
26   CommuataiveType := "Commutative"
27 else if (weakcommutative = true)  $\wedge$  (commutative = false) then
28   CommuataiveType := "Weak Commutative"
29 else CommuataiveType := "Non – Commutative"
30 end if
31 return CommuataiveType + BaseType

```

Procedure call: WhatIsTypeOf(\circ, H)

The following procedures are written in Maple based on algorithms in this subsection.

```

IsClosed:=proc(hypero::procedure,K::set,$)::boolean;
  local b::boolean,x,y;
  b:=true;
  for x in K do
    for y in K do
      if not(aob(hypero,x,y) subset K) then
        b:=false;
        break;
        break;
      end if;
    end do;
  end do;
  return b;
end proc;
#-----
IsAssociative:=proc(hypero::procedure,K::set,$)::boolean;
  local b::boolean,x,y,z;
  b:=true;
  for x in K do
    for y in K do
      for z in K do
        if evalb(aoB(hypero,x,aob(hypero,y,z))<>Aob(hypero,aob(hypero,x,y),z)) then
          b:=false;
          break;
          break;
          break;
        end if;
      end do;
    end do;
  end do;

```

```

    end do;
  end do;
end do;
return b;
end proc:
#-----
IsWeakAssociative:=proc(hypero::procedure,K::set,$)::boolean;
local b::boolean,x,y,z;
b:=true;
for x in K do
  for y in K do
    for z in K do
      if (aoB(hypero,x,aob(hypero,y,z)) intersect Aob(hypero,aob(hypero,x,y),z))={ } then
        b:=false;
        break;
        break;
        break;
      end if;
    end do;
  end do;
end do;
return b;
end proc:
#-----
IsCommutative:=proc(hypero::procedure,K::set,$)::boolean;
local b::boolean,x,y;
b:=true;
for x in K do
  for y in K do
    if aob(hypero,x,y)<>aob(hypero,y,x) then
      b:=false;
      break;
      break;
    end if;
  end do;
end do;
return b;
end proc:
#-----
IsWeakCommutative:=proc(hypero::procedure,K::set,$)::boolean;
local b::boolean,x,y;
b:=true;
for x in K do
  for y in K do
    if (aob(hypero,x,y) intersect aob(hypero,y,x))={ } then
      b:=false;
      break;
      break;
    end if;
  end do;
end do;

```

```

    end do;
end do;
return b;
end proc:
#-----
IsReproduction:=proc(hypero::procedure,K::set,$)::boolean;
local b::boolean,a;
b:=true;
for a in K do
  if aoB(hypero,a,K)<>K then
    b:=false;
    break;
  elif Aob(hypero,K,a)<>K then
    b:=false;
    break;
  end if;
end do;
return b;
end proc:
#-----
IsHypergroupoid:=proc(hypero::procedure,H::set,$)::boolean;
local b::boolean,x,y,T::set;
b:=true;
if H={} then
  b:=false;
else
  for x in H do
    for y in H do
      T:=aob(hypero,a,b);
      if T={} then
        b:=false;
        break;
        break;
      elif not (T subset H) then
        b:=false;
        break;
        break;
      end if;
    end do;
  end do;
end if;
return b;
end proc:
#-----
with(StringTools):
#-----
WhatIsTypeOf:=proc(hypero::procedure,H::set,$)::string;
local BaseType::string,CommuataiveType::string,associative::boolean,weakassociative::
boolean,commutative::boolean,weakcommutative::boolean,reproduction::boolean;

```

```

associative:=IsAssociative(hypero,H);
if associative=true then weakassociative:=true;
else weakassociative:=IsWeakAssociative(hypero,H);
end if;
commutative:=IsCommutative(hypero,H);
if commutative=true then weakcommutative:=true;
else weakcommutative:=IsWeakCommutative(hypero,H);
end if;
reproduction:=IsReproduction(hypero,H);
if (associative and weakassociative and reproduction) then
BaseType:="Hypergroup";
elif (weakassociative and reproduction) and (not associative) then
BaseType:="Hv-group";
elif (associative and weakassociative) and (not reproduction) then
BaseType:="Semihypergroup";
elif weakassociative and ((not associative) and (not reproduction)) then
BaseType:="Hv-semigroup";
elif reproduction and ((not associative) and (not weakassociative)) then
BaseType:="Quasihypergroup";
else BaseType:="Hypergroupoid";
end if;
if (commutative and weakcommutative) then
CommuatativeType:="Commutative";
elif weakcommutative and (not commutative) then
CommuatativeType:="Weak Commutative";
else CommuatativeType:="Non-Commutative";
end if;
return Join([CommuatativeType,BaseType], " ");
end proc;
#-----

```

To call the above procedures in Maple, it can be done like the following commands:

```

IsClosed(hypero,K);
WhatIsTypeOf(hypero,H);

```

3.3 An algorithm for morphisms in hypergroupoids

In this subsection, we present an algorithm for morphisms. The algorithm in this subsection can be easily extended to other types of morphisms in other algebraic hyperstructures. Required definition are given from [5, 7, 3].

Let (H_1, \circ) and (H_2, \star) be two hypergroupoids. A map $f : H_1 \rightarrow H_2$ is called

- a *homomorphism* or *inclusion homomorphism* if we have $f(x \circ y) \subseteq f(x) \star f(y)$ for all $x, y \in H_1$;
- a *good (strong) homomorphism* if we have $f(x \circ y) = f(x) \star f(y)$ for all $x, y \in H_1$;
- an *isomorphism* if it is one to one and onto good homomorphism.

If f is an isomorphism, then H_1 and H_2 are said to be *isomorphic*, which is denoted by $H_1 \cong H_2$.

Remark 3.3. If $f : H_1 \rightarrow H_2$ is a map on the *finite* sets H_1 and H_2 , then the necessary and sufficient condition for f to be onto is that $|f(H_1)| = |H_2|$, which $f(H_1) = \{f(x)|x \in H_1\}$, and to be one to one is that $|f(H_1)| = |H_1|$. Therefore, f is one to one and onto if we have $|f(H_1)| = |H_1| = |H_2|$.

Now, using Remark 3.3 in Algorithm 12, we can easily determine the type of a mapping between two hypergroupoid (H_1, \circ) and (H_2, \star) .

Algorithm 12: Determining the type of a mapping $f : H_1 \rightarrow H_2$ between two hypergroupoids (H_1, \circ) and (H_2, \star)

```

1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: Is  $f$  a mapping from  $(H_1, \circ)$  to  $(H_2, \star)$ ?
3 Procedure: IsMapping( $\circ : procedure, H_1 : set, \star : procedure, H_2 : set, f : procedure$ ) :boolean
4  $b := true$ 
5 if  $(H_1 = \emptyset) \vee (H_2 = \emptyset)$  then
6    $b := false$ 
7 else
8   for  $x \in H_1$  do
9     if  $f(x) \notin H_2$  then
10       $b := false$ 
11      break
12     end if
13   end for
14 end if
15 return  $b$ 
16


---


1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: Is mapping  $f$  a homomorphism from  $(H_1, \circ)$  to  $(H_2, \star)$ ?
3 Procedure: IsHomomorphism( $\circ : procedure, H_1 : set, \star : procedure, H_2 : set, f : procedure$ ) :boolean
4  $b := true$ 
5 for  $x \in H_1$  do
6   for  $y \in H_1$  do
7      $fxoy := \emptyset$ 
8      $xoy := x \circ y$  /*  $x \circ y = aob(\circ, x, y)$  */
9     for  $z \in xoy$  do
10       $fxoy := fxoy \cup \{f(z)\}$  /*  $fxoy$  is equal to  $f(x \circ y)$  */
11     end for
12     if  $fxoy \not\subseteq f(x) \star f(y)$  then /*  $f(x) \star f(y) = aob(\star, f(x), f(y))$  */
13        $b := false$ 
14       break
15     end if
16   end for
17 end for
18 return  $b$ 
19


---


1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: Is mapping  $f$  a good homomorphism from  $(H_1, \circ)$  to  $(H_2, \star)$ ?
3 Procedure: IsGoodHomomorphism( $\circ : procedure, H_1 : set, \star : procedure, H_2 : set, f : procedure$ ) :boolean
4  $b := true$ 
5 for  $x \in H_1$  do
6   for  $y \in H_1$  do
7      $fxoy := \emptyset$ 
8      $xoy := x \circ y$  /*  $x \circ y = aob(\circ, x, y)$  */

```

```

9   for  $z \in xoy$  do
10       $f_{xoy} := f_{xoy} \cup \{f(z)\}$  /*  $f_{xoy}$  is equal to  $f(x \circ y)$  */
11   end for
12   if  $f_{xoy} \neq f(x) \star f(y)$  then /*  $f(x) \star f(y) = aob(\star, f(x), f(y))$  */
13       $b := false$ 
14      break
15   end if
16 end for
17 end for
18 return  $b$ 
19


---


1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: Is mapping  $f$  onto from  $(H_1, \circ)$  to  $(H_2, \star)$ ?
3 Procedure:  $IsOnto(\circ : procedure, H_1 : set, \star : procedure, H_2 : set, f : procedure) : boolean$ 
4  $b := true$ 
5  $fH_1 := \emptyset$ 
6 for  $x \in H_1$  do
7    $fH_1 := fH_1 \cup \{f(x)\}$  /* Set  $fH_1$  is equal to  $f(H_1)$  */
8 end for
9 if  $|fH_1| \neq |H_2|$  then
10   $b := false$ 
11 end if
12 return  $b$ 
13


---


1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: Is mapping  $f$  one to one from  $(H_1, \circ)$  to  $(H_2, \star)$ ?
3 Procedure:  $IsOneToOne(\circ : procedure, H_1 : set, \star : procedure, H_2 : set, f : procedure) : boolean$ 
4  $b := true$ 
5  $fH_1 := \emptyset$ 
6 for  $x \in H_1$  do
7    $fH_1 := fH_1 \cup \{f(x)\}$  /* Set  $fH_1$  is equal to  $f(H_1)$  */
8 end for
9 if  $|fH_1| \neq |H_1|$  then
10   $b := false$ 
11 end if
12 return  $b$ 
13


---


1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: Is mapping  $f$  an isomorphism from  $(H_1, \circ)$  to  $(H_2, \star)$ ?
3 Procedure:  $IsIsomorphism(\circ : procedure, H_1 : set, \star : procedure, H_2 : set, f : procedure) : boolean$ 
4  $b := true$ 
5 if  $IsGoodHomomorphism(\circ, H_1, \star, H_2, f) = false$  then  $b := false$ 
6 else if  $IsOnto(\circ, H_1, \star, H_2, f) = false$  then  $b := false$ 
7 else if  $|H_1| \neq |H_2|$  then  $b := false$ 
8 end if
9 return  $b$ 
10


---


1 Input: Hyperoperation  $\circ$ , Set  $H_1$ , Hyperoperation  $\star$ , Set  $H_2$ , Mapping  $f : H_1 \rightarrow H_2$ 
2 Output: What is the type of mapping  $f$  from  $(H_1, \circ)$  to  $(H_2, \star)$ ?

```

```

3 Procedure: WhatTypeOfMapping( $\circ$  : procedure,  $H_1$  : set,  $\star$  : procedure,  $H_2$  : set,  $f$  : procedure) : boolean
4 goodhomo := IsGoodHomomorphism( $\circ$ ,  $H_1$ ,  $\star$ ,  $H_2$ ,  $f$ )
5 if goodhomo = true then
6   homo := true
7 else homo := IsHomomorphism( $\circ$ ,  $H_1$ ,  $\star$ ,  $H_2$ ,  $f$ )
8 end if
9 onto := IsOnto( $\circ$ ,  $H_1$ ,  $\star$ ,  $H_2$ ,  $f$ )
10 cardH1 := | $H_1$ |
11 cardH2 := | $H_2$ |
12 BaseType := ""
13 SubType := ""
14 if goodhomo = true then
15   BaseType := "GoodHomomorphism"
16 else if (goodhomo = false)  $\wedge$  (homo = true) then
17   BaseType := "Homomorphism"
18 else BaseType := "Mapping"
19 end if
20 if (goodhomo = true)  $\wedge$  (onto = true)  $\wedge$  (cardH1 = cardH2) then
21   BaseType := "Isomorphism"
22   SubType := ""
23 else if (onto = true)  $\wedge$  (cardH1 = cardH2) then
24   SubType := "One to one and onto"
25 else if (onto = true)  $\wedge$  (cardH1  $\neq$  cardH2) then
26   SubType := "Onto"
27 else
28   onetoone := IsOneToOne( $\circ$ ,  $H_1$ ,  $\star$ ,  $H_2$ ,  $f$ )
29   if (onto = false)  $\wedge$  (onetoone = true) then
30     SubType := "One to one"
31   else SubType := ""
32   end if
33 end if
34 return SubType + BaseType

```

Procedure call: *IsMapping*(\circ , H_1 , \star , H_2 , f), *IsHomomorphism*(\circ , H_1 , \star , H_2 , f),
IsGoodHomomorphism(\circ , H_1 , \star , H_2 , f), *IsOnto*(\circ , H_1 , \star , H_2 , f), *IsOneToOne*(\circ , H_1 , \star , H_2 , f),
IsIsomorphism(\circ , H_1 , \star , H_2 , f), *WhatTypeOfMapping*(\circ , H_1 , \star , H_2 , f)

To call procedure *WhatTypeOfMapping* in Algorithm 12, we must first show f is a mapping (for example by procedure *IsMapping*), and then determine its type by procedure *WhatTypeOfMapping*.

The following procedures are written in Maple based on Algorithm 12.

```

with(StringTools):
#-----
IsMapping:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::procedure,$)::
  boolean;
  local b::boolean,x;
  b:=true;
  if (H1={} or H2={}) then
    b:=false;
  else

```

```

for x in H1 do
  if not (fmap(x) in H2) then
    b:=false;
    break;
  end if;
end do;
end if;
return b;
end proc:
#-----
IsHomomorphism:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::procedure
,$)::boolean;
local b::boolean,x,y,z,xoy,fxoy;
b:=true;
for x in H1 do
  for y in H2 do
    fxoy:={};
    xoy:=aob(hypero1,x,y);
    for z in xoy do
      fxoy:=fxoy union {fmap(z)};
    end do;
    if not(fxoy subset aob(hypero2,fmap(x),fmap(y))) then
      b:=false;
      break;
    end if;
  end do;
end do;
return b;
end proc:
#-----
IsGoodHomomorphism:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::
procedure,$)::boolean;
local b::boolean,x,y,z,xoy,fxoy;
b:=true;
for x in H1 do
  for y in H2 do
    fxoy:={};
    xoy:=aob(hypero1,x,y);
    for z in xoy do
      fxoy:=fxoy union {fmap(z)};
    end do;
    if fxoy<>aob(hypero2,fmap(x),fmap(y)) then
      b:=false;
      break;
    end if;
  end do;
end do;
return b;
end proc:

```

```

#-----
IsOnto:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::procedure,$)::
  boolean;
  local b::boolean,x,fH1;
  b:=true;
  for x in H1 do
    fH1:=fH1 union {f(x)};
  end do;
  if numelems(fH1)<>numelems(H2) then
    b:=false;
  end if;
  return b;
end proc;
#-----
IsOneToOne:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::procedure,$)
  ::boolean;
  local b::boolean,x,fH1;
  b:=true;
  for x in H1 do
    fH1:=fH1 union {f(x)};
  end do;
  if numelems(fH1)<>numelems(H1) then
    b:=false;
  end if;
  return b;
end proc;
#-----
IsIsomorphism:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::procedure,
  $)::boolean;
  local b::boolean;
  b:=true;
  if not IsGoodHomomorphism(hypero1,H1,hypero2,H2,fmap) then b:=false;
  elif IsOnto(hypero1,H1,hypero2,H2,fmap) then b:=false;
  elif numelems(H1)<>numelems(H2) then b:=false;
  end if;
  return b;
end proc;
#-----
WhatTypeOfMapping:=proc(hypero1::procedure,H1::set,hypero2::procedure,H2::set,fmap::
  procedure,$)::boolean;
  local goodhomo::boolean,homo::boolean,onto::boolean,onetoone::boolean,cardH1,cardH2,
    BaseType::string,SubType::string;
  goodhomo:=IsGoodHomomorphism(hypero1,H1,hypero2,H2,fmap);
  if goodhomo then
    homo:=true;
  else homo:=IsHomomorphism(hypero1,H1,hypero2,H2,fmap);
  end if;
  onto:=IsOnto(hypero1,H1,hypero2,H2,fmap);
  cardH1:=numelems(H1);

```

```

cardH2:=numelems(H2);
BaseType:="";
SubType:="";
if goodhomo then BaseType:="GoodHmomorphism";
elif (not goodhomo) and homo then BaseType:="Hmomorphism";
else BaseType:="Mapping";
end if;
if goodhomo and onto and (cardH1=cardH2) then
  BaseType:="Isomorphism";
  SubType:="";
elif onto and (cardH1=cardH2) then SubType:="One to one and onto";
elif onto and (cardH1<>cardH2) then SubType:="Onto";
else
  onetoone:=IsOneToOne(hypero1,H1,hypero2,H2,fmap);
  if (not onto) and onetoone then
    SubType:="One to one";
  else SubType:="";
  end if;
end if;
return Join([SubType,BaseType], " ");
end proc;
#-----

```

To call the above procedures in Maple, it can be done like the following commands:

```

IsMapping(hypero1,H1,hypero2,H2,fmap);
WhatTypeOfMapping(hypero1,H1,hypero2,H2,fmap);

```

4 Conclusion

In this paper, first, we presented two methods to define a hypergroupoid by algorithm (subsection 3.1). These methods are simple, but any methods can be used for this, with the condition that the number and type of inputs and output are observed. Then, we presented algorithms for checking some basic features of algebraic hyperstructures with one hyperoperation (hypergroupoids) and determining the type of algebraic hyperstructures (subsection 3.2). The features that we provided algorithm to check are: being closed under \circ , associativity, weak associativity, commutativity, weak commutativity, establishing the reproduction axiom, determining the type of a hypergroupoid (H, \circ) . Also, we present an algorithm to determine the type of morphisms in hypergroupoids (subsection 3.3).

Although in this paper, we presented algorithms only for algebraic hyperstructures with one hyperoperation, but using the methods provided in the algorithms, it is easy to provide algorithms for other algebraic hyperstructures.

In this paper, we did not examine the complexity and optimization of the algorithms, and these issues can be explored in future research. It is also possible to study the application of these algorithms in interdisciplinary research. The presentation of algorithms based on definitions encourages people to investigate the effect of these algorithms in teaching the desired concepts in algebraic hyperstructures.

5 Data Availability Statement

NA

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